





# Integrating Studierstube and DWARF

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### **Component-based approaches**

Studierstube C++ classes on top of Open Inventor (OIV) Object-oriented scene graph Geometric information Active interaction objects Distribution of applications Shared scene graph through DIV OpenTracker Library operates on tracking data Breaks up transformations defined by XML



#### **Component-based approaches**

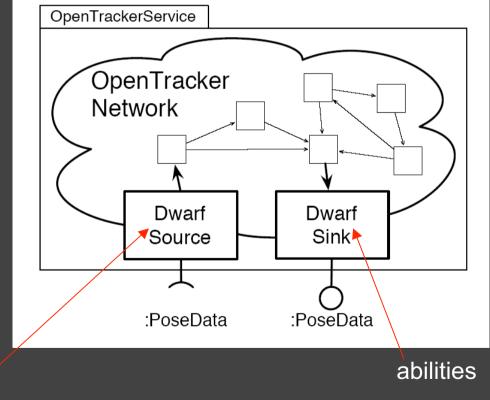
DWARF Basic unit is distributed service needs, abilities Services bundled with hardware in units Strong modular design Easily extended by adding new components Adapters OpenTracker <-> DWARF Open Inventor <->DWARF



## **OpenTracker network as DWARF service**

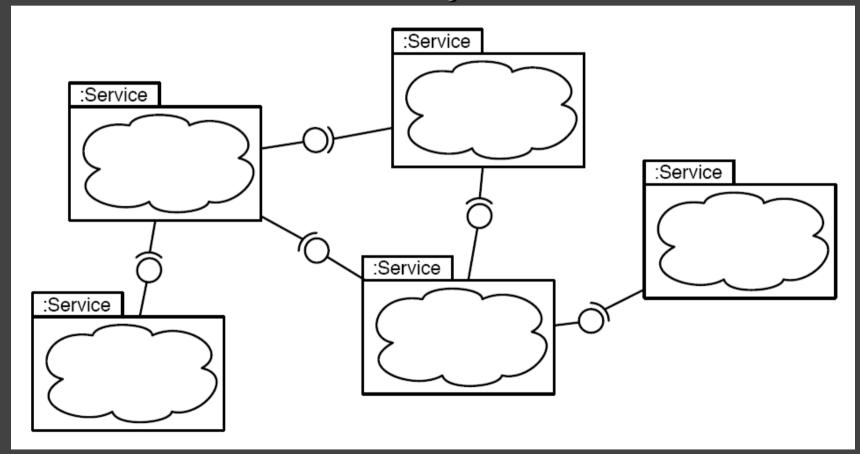
OpenTracker extensible by modules

interface devices algorithms other frameworks **DWARF** module Implements nodes DwarfSink DwarfSource Complete DWARF service needs



## DWARF connecting different OpenTracker networks

Smaller networks for dynamic scenarios



Joseph Newman

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# **DWARF service embedded in an MOIV scene graph**

OIV supports nodes in a scene graph Contain *Fields* of predefined types *DwarfService* node is single DWARF service **Fields** configure service parameters Contains lists of subnodes needs, DwarfNeed abilities, DwarfAbility Studierstube can express DWARF service within scene graph



## Conclusion

Wider choice of tools leads to more elegant solutions

Reduce overheads

device drivers, filter objects realised only once

Existing local static setups

Defined by OpenTracker

Dynamically combined using DWARF

 Large-scale Ubiquitous Computing Environments Encourage interoperability with other AR frameworks

Joseph Newman

## Thankyou



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